

# Self-Supervised Models of Vision + Language

CSCI 601 471/671

NLP: Self-Supervised Models

<https://self-supervised.cs.jhu.edu/sp2023/>



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UNIVERSITY

# Logistics update

- We recommended few projects for revision. Due on Monday noon.
  - Please talk to us if you need more brainstorming to scope your proposal better.
- Each team is assigned to a mentor (we will email you about the assignment).
- Each team is responsible to schedule meeting time with their mentor.
- Our suggestion: meet with them at least once every 10 days.
- Starting next week: no TA/CA office hours.
- We will have external speakers next week!

# Attention Is All You Need

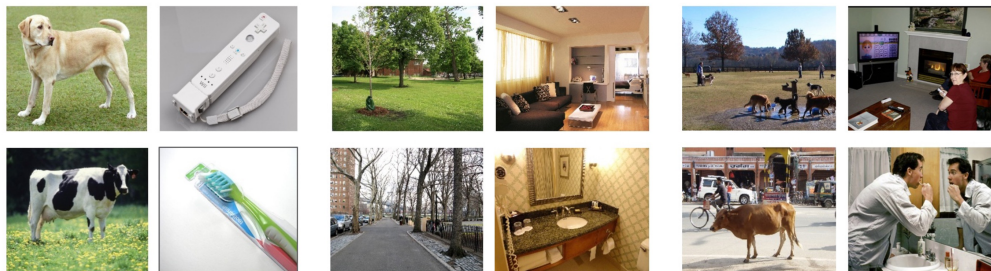
- Transformers are eating the world
- SOTA performance across a range of NLP tasks
  - ...QA
  - ...summarization
  - ... paraphrasing
- **Is Attention all you need?**
  - Everything thus far has been text
  - What about other modalities, e.g., images?
  - What about multi-modal settings, e.g., captioned images?

# Today's Talk

- Resources, datasets, & problems of interest
- Models & architectures
- Challenges & envisioned future

# COCO, VQA, CLEVR, oh my

## Common Objects In Context (2014)



(a) Iconic object images

(b) Iconic scene images

(c) Non-iconic images

- Object detection, segmentation, key-point detection, and captioning
- ~330K Images

# COCO, VQA, CLEVR, oh my

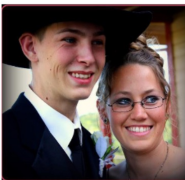
## Visual Question Answering (2017)

Who is wearing glasses?

man

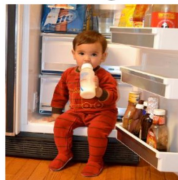


woman

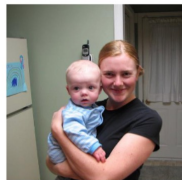


Where is the child sitting?

fridge



arms

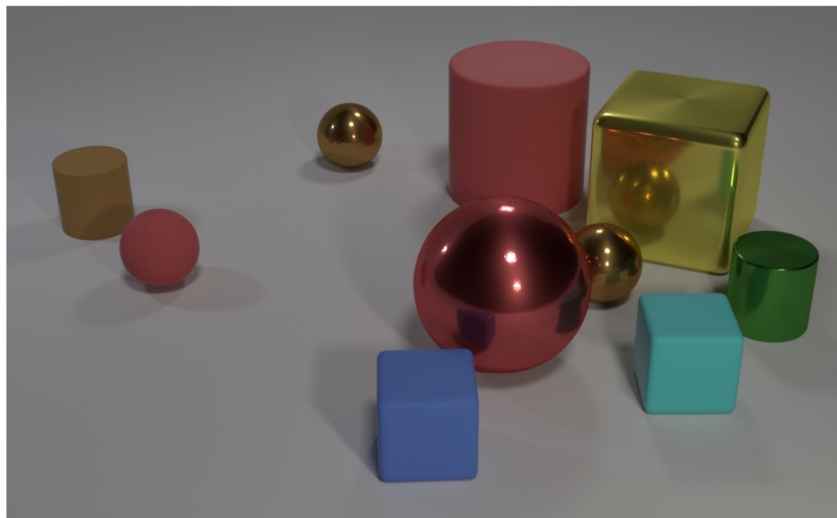


- Open-ended questions about images
- ~265K Images, at least 3 questions per image, "gold" answers

# COCO, VQA, CLEVR, oh my

## CLEVER (2017)

- "strong biases that models can exploit to correctly answer questions without reasoning"
- ~100K Images
- ~865K Questions
  - Answers to all train/val questions



- Q: Are there an equal number of large things and metal spheres?  
Q: What size is the cylinder that is left of the brown metal thing that is left of the big sphere? Q: There is a sphere with the same size as the metal cube; is it made of the same material as the small red sphere?  
Q: How many objects are either small cylinders or metal things?

# Let's Consider Images – How to Encode?





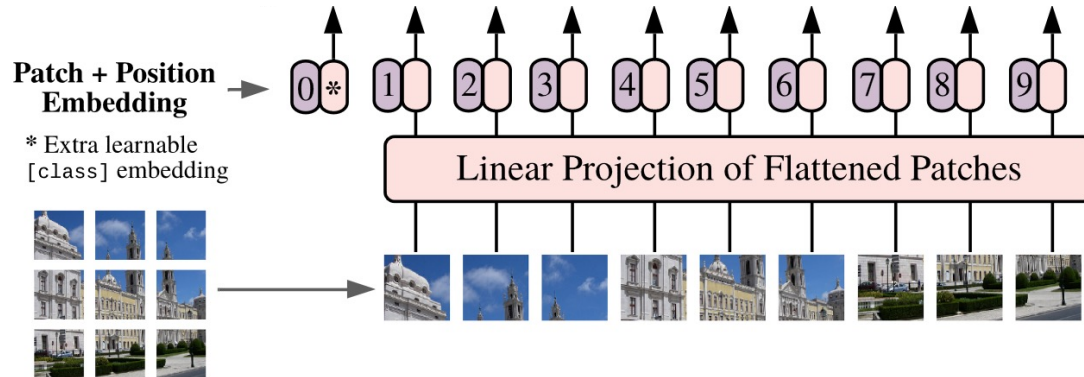
# Let's Consider Images - Vision Transformer

## Patch + Position Embedding

\* Extra learnable  
[class] embedding

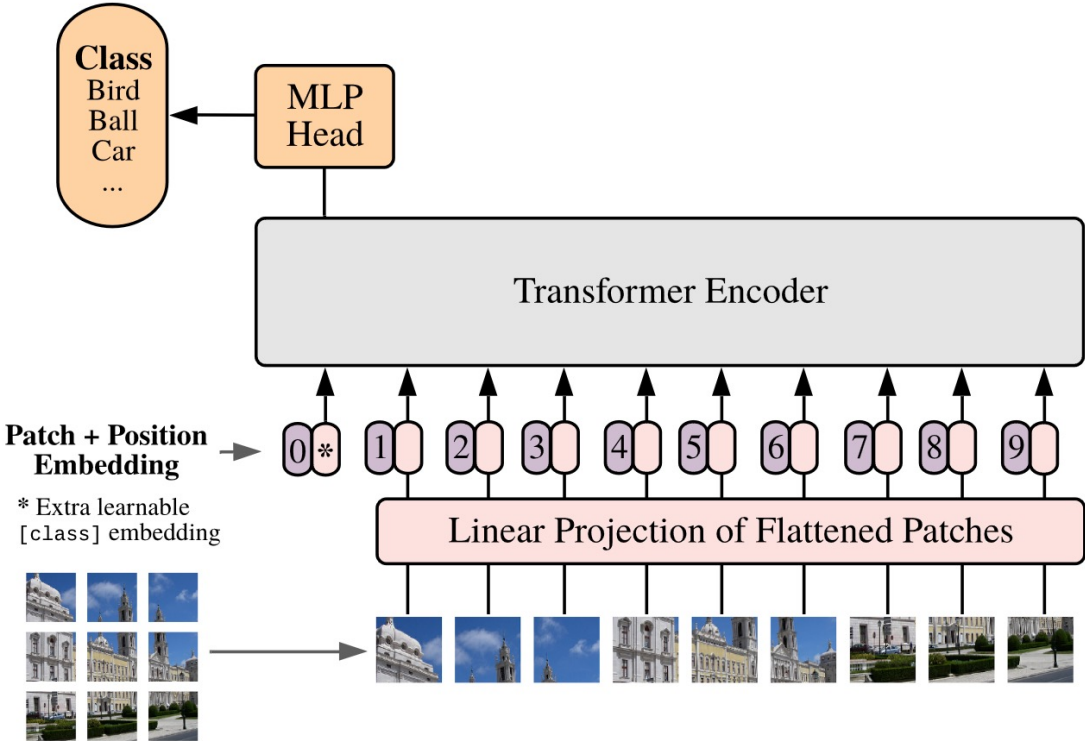


# Let's Consider Images - Vision Transformer



# Let's Consider Images - Vision Transformer

## Vision Transformer (ViT)



[An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale, 2020]

# What about paired image-text – How to Encode?



Basilica of St. John Lateran

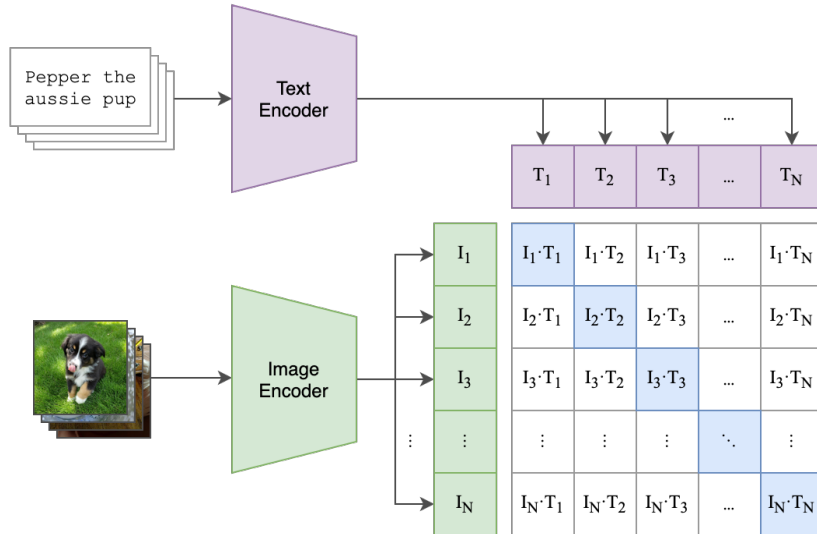


House with Chimeras – Kiev

# Contrastive Language–Image Pre-training (CLIP)

Given a batch of  $N$  (image, text) pairs, predict which of the  $N \times N$  possible (image, text) pairings across a batch occurred

## (1) Contrastive pre-training



```
# image_encoder - ResNet or Vision Transformer
# text_encoder - CBOW or Text Transformer
# I[n, h, w, c] - minibatch of aligned images
# T[n, l] - minibatch of aligned texts
# W_i[d_i, d_e] - learned proj of image to embed
# W_t[d_t, d_e] - learned proj of text to embed
# t - learned temperature parameter

# extract feature representations of each modality
I_f = image_encoder(I) #[n, d_i]
T_f = text_encoder(T) #[n, d_t]

# joint multimodal embedding [n, d_e]
I_e = l2_normalize(np.dot(I_f, W_i), axis=1)
T_e = l2_normalize(np.dot(T_f, W_t), axis=1)

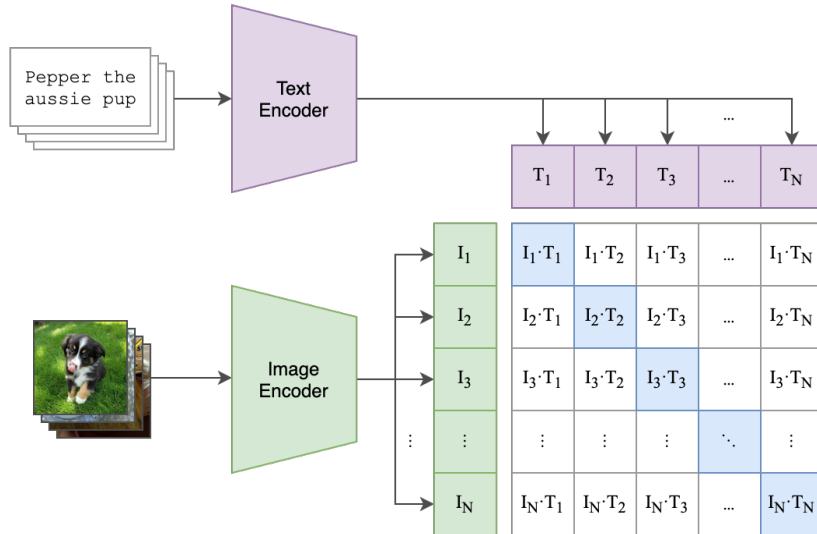
# scaled pairwise cosine similarities [n, n]
logits = np.dot(I_e, T_e.T) * np.exp(t)

# symmetric loss function
labels = np.arange(n)
loss_i = cross_entropy_loss(logits, labels, axis=0)
loss_t = cross_entropy_loss(logits, labels, axis=1)
loss = (loss_i + loss_t)/2
```

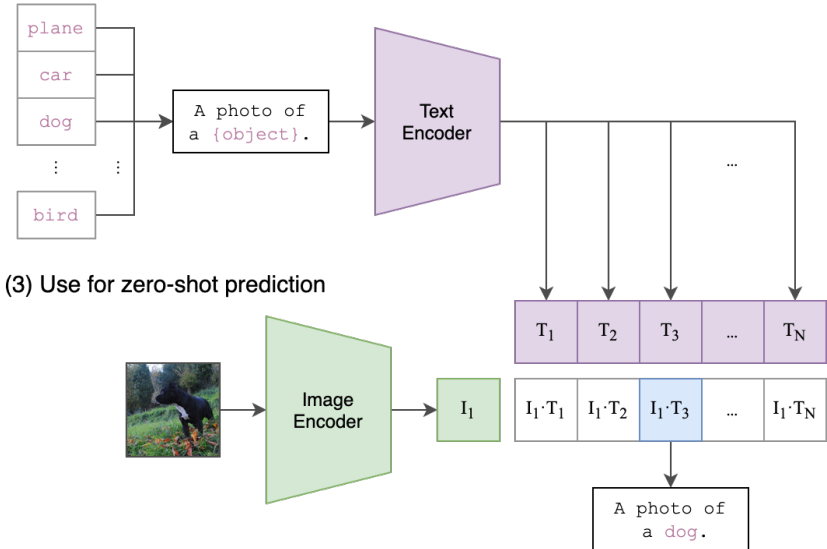
# Contrastive Language–Image Pre-training (CLIP)

Consider classifying photos of dogs vs cats - for each image, check if CLIP predicts text description “a photo of a *dog*” or “a photo of a *cat*” is more likely to be paired with it

(1) Contrastive pre-training



(2) Create dataset classifier from label text



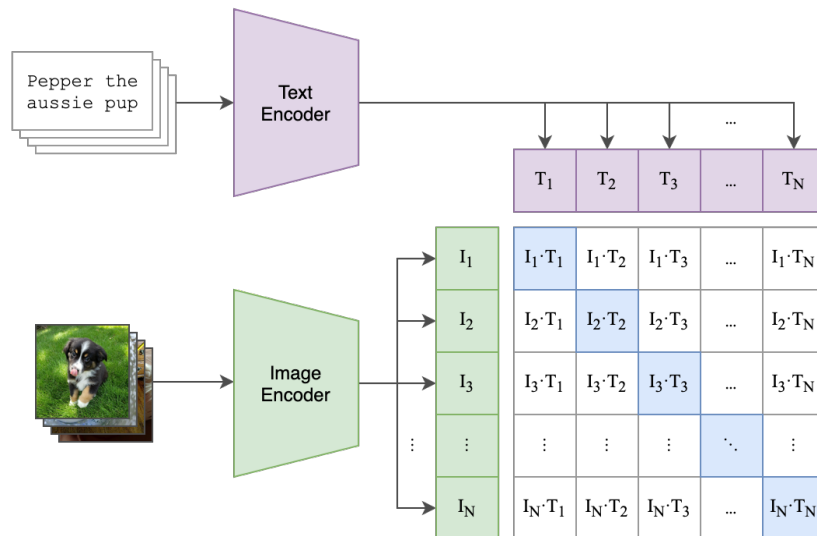
(3) Use for zero-shot prediction

# What can CLIP do?

CLIP evaluates associations between image-text pairs:

- Image Classification
- Image Searching
- Controllable Caption Generation

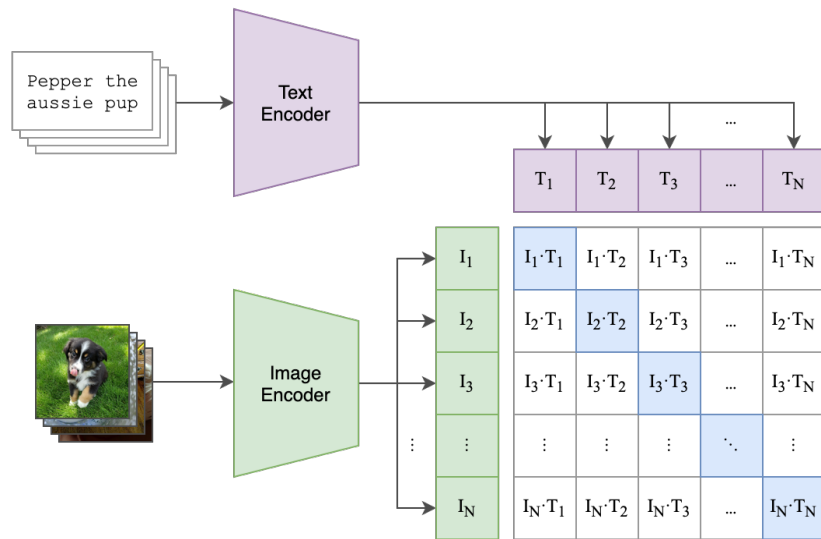
(1) Contrastive pre-training



# What can't CLIP do?

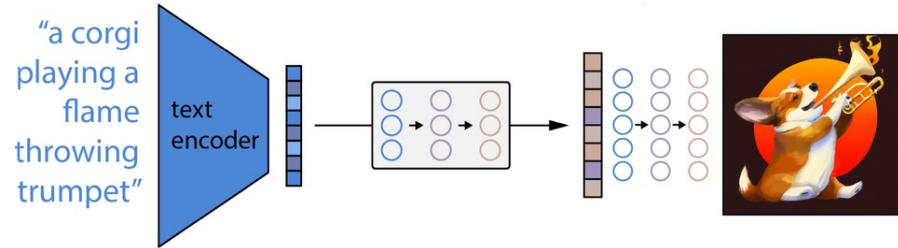
- No generation capabilities
- Prompting / In-Context Learning
  - Few-shot captioning

(1) Contrastive pre-training





# Text-to-Image



# DALL-E

- First, a text prompt is input into a **text encoder** that is trained to map the prompt to a representation space.

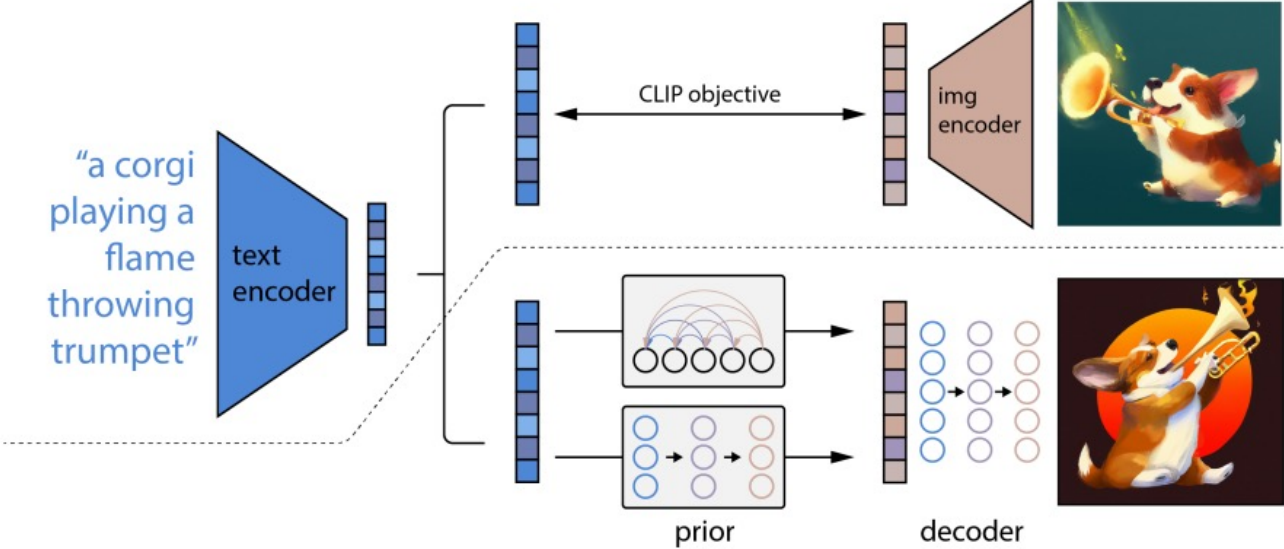
# DALL-E

- First, a text prompt is input into a **text encoder** that is trained to map the prompt to a representation space.
- Next, a **prior** maps the text encoding to a corresponding **image encoding** that captures the semantic information of the prompt contained in the text encoding.

# DALL-E

- First, a text prompt is input into a **text encoder** that is trained to map the prompt to a representation space.
- Next, a **prior** maps the text encoding to a corresponding **image encoding** that captures the semantic information of the prompt contained in the text encoding.
- Finally, an **image decoder** stochastically generates an image which is a visual manifestation of this semantic information.

# DALL-E



# Multimodal Prompting

- CLIP addresses ImageNet, but what if we introduce novel images / text / classes?
- DALL-E addresses controllable image generation, but still no ICL
- LLMs are transferrable to new tasks via prompting with examples
- Can we do the same thing in a multimodal setting, e.g. vision + language?

# Multimodal Few-Shot Learning with Frozen Language Models

- First, consider a pretrained LLM
  - GPT-2-esque (7B)
  - Pretrained on  $C_4$
- Next, consider a vision encoder
  - Input images (e.g.  $W \times H \times C$ )
  - Output  $N$  tokens

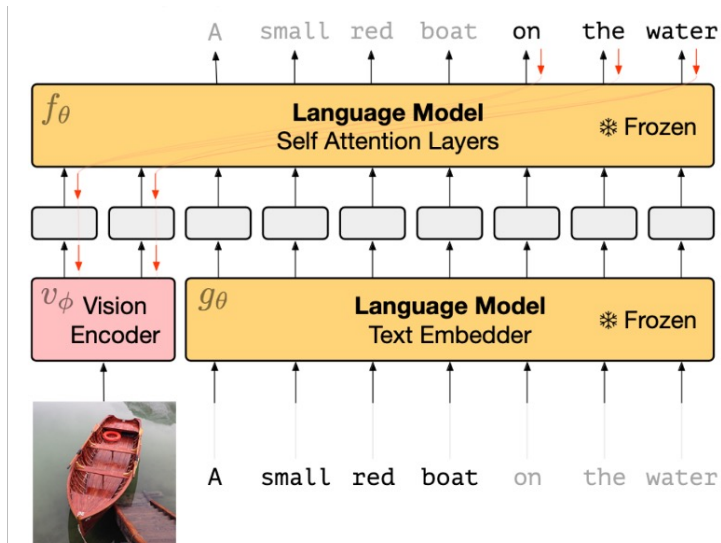


Figure 2: Gradients through a frozen language model's self attention layers are used to train the vision encoder.

# Multimodal Few-Shot Learning with Frozen Language Models

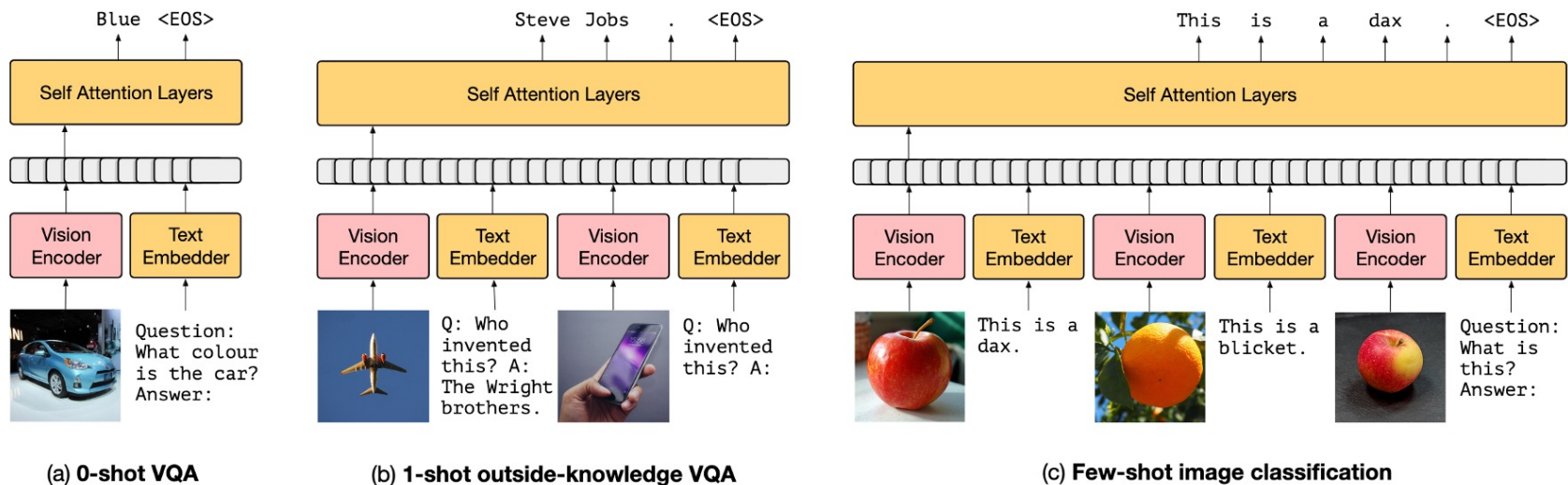


Figure 3: Inference-Time interface for *Frozen*. The figure demonstrates how we can support (a) visual question answering, (b) outside-knowledge question answering and (c) few-shot image classification via in-context learning.



GPT-4

User Can you explain this meme?

Sometimes I just look at pictures of the earth from space and I marvel at how beautiful it all is.



GPT-4 This meme is a joke that combines two unrelated things: pictures of the earth from space and chicken nuggets.

The text of the meme suggests that the image below is a beautiful picture of the earth from space. However, the image is actually of chicken nuggets arranged to vaguely resemble a map of the world.

The humor in this meme comes from the unexpected juxtaposition of the text and the image. The text sets up an expectation of a majestic image of the earth, but the image is actually something mundane and silly.

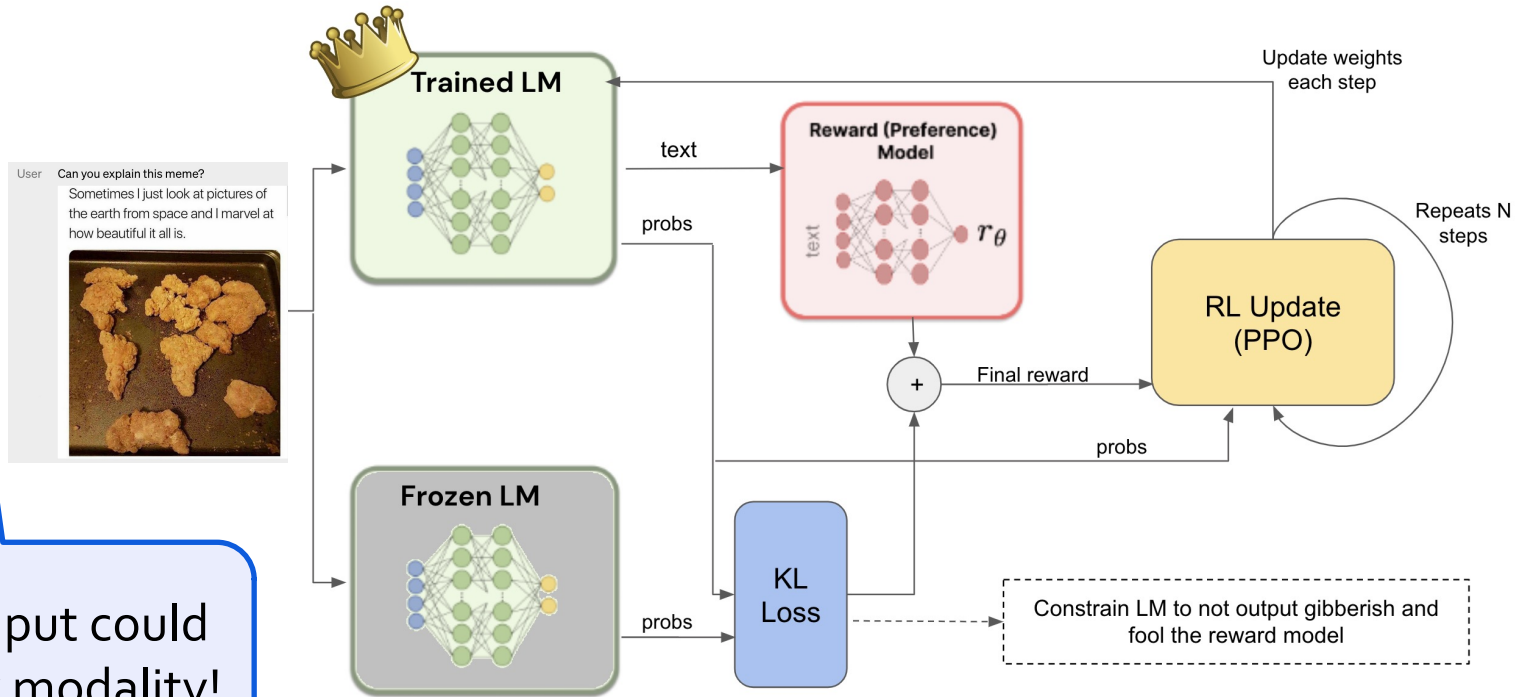
User What is unusual about this image?



Source: [Barnorama](#)

GPT-4 The unusual thing about this image is that a man is ironing clothes on an ironing board attached to the roof of a moving taxi.

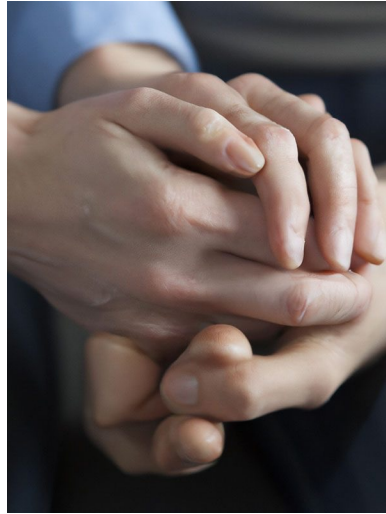
# Multimodal - RLHF



The input could be any modality!

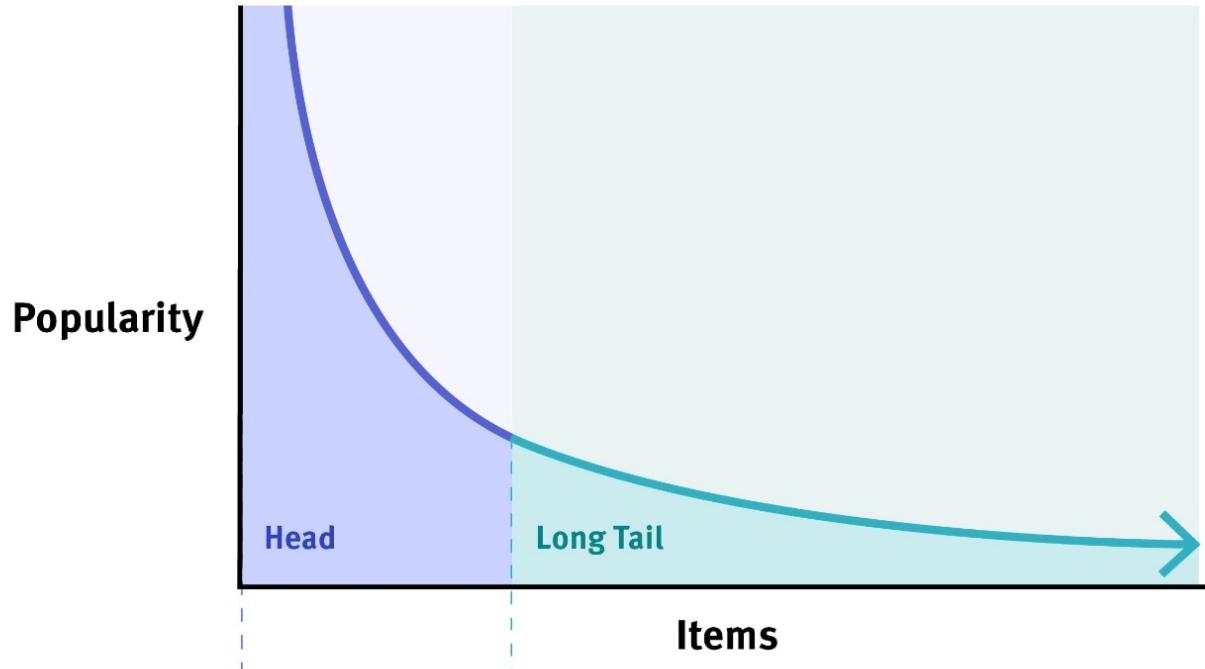
Challenges we still face

*Models' quality depend on frequency of patterns*



# Challenges we still face - The long tail

*Most things are infrequent*



# Envisioning the future

- More modalities — combinations of video (2D, 3D), text, code, etc.
- Large models and more efficient scaling
- More breath — more data and more types of data
- Interaction with physical world — models with hands and actuators
- Better personalization — these agents should serve your 🙌 needs
- Better human-machine teaming
  - CoPilot for coding
  - CoPilot for writing
  - ....
  - CoPilot for life!!!